Neural Computation : Exercise Sheet 3

John A. Bullinaria - 2015

The following questions are of the kind that may come up in the exam this year. They are designed to help you monitor your progress – try to answer the questions without your notes, and then use your notes to check whether your answers are correct. The percentages indicate the corresponding fraction of a 1.5 hour exam.

Question 1

- (a) Explain how a gradient descent algorithm can be used to train a Multi-Layer Perceptron neural network. [8%]
- (b) Outline the principal techniques that can be applied to speed up the training when using such algorithms. Which of them is usually easiest, and why? [7%]
- (c) Outline the principal techniques for improving the generalization ability of neural networks trained in that way. Which of them is usually easiest, and why? [10%]

Question 2

(a) In the context of feed-forward neural networks, explain what the following equation, and each symbol in it, represents:

$$E = -\sum_{p} \left[targ^{p} . \log(out^{p}) + (1 - targ^{p}) . \log(1 - out^{p}) \right]$$
[5%]

- (b) Describe the basic ideas underlying *gradient descent learning algorithms*, and how and when the above equation would be used for such training. [8%]
- (c) Explain how, in general, one could estimate the expected generalization ability of a trained neural network. [6%]
- (d) Describe one way in which the above equation could be modified to improve the generalization ability of the trained neural network. [6%]

Question 3

- (a) What is *k-fold cross validation*? Explain the assumptions involved and how it is relevant to the optimization of neural network generalization performance. [8%]
- (b) Describe in detail how and why *early stopping* can be used to improve generalization with back-propagation training, and how the stopping point can be determined. [12%]
- (c) What are the major advantages of early stopping over alternative procedures for improving generalization? [5%]

Question 4

(a) Explain in words what the various terms in the following equation signify, and what the equation as a whole tells us:

$$\mathcal{F}_{D}\left[\left(\mathcal{F}[y \mid x_{i}] - net(x_{i}, W, D)\right)^{2}\right]$$

$$= \left(\mathcal{F}_{D}\left[net(x_{i}, W, D)\right] - \mathcal{F}[y \mid x_{i}]\right)^{2} + \mathcal{F}_{D}\left[\left(net(x_{i}, W, D) - \mathcal{F}_{D}\left[net(x_{i}, W, D)\right]\right)^{2}\right]$$

$$= (bias)^{2} + (variance)$$
[10%]

- (b) Using a simple example, such as a Multi-Layer Perceptron trained to perform function approximation (regression), describe the extreme cases of *over-fitting* and *under-fitting* within the framework underlying the above equation. [5%]
- (c) With reference to the above equation, explain three distinct approaches that might lead to improved generalization ability for a trained Multi-Layer Perceptron. [10%]

Question 5

- (a) In the context of Multi-Layer Perceptron (MLP) training, explain carefully the relation between *Weight Decay* and cost function *Regularization*. [5%]
- (b) Give an intuitive argument of why one might expect weight decay to help improve the generalization ability of an MLP. [5%]
- (c) Explain why one should not also decay the thresholds/biases. [4%]
- (d) Describe how one could use a *validation set* to choose the appropriate level of weight decay for a given classification problem. [5%]
- (e) Briefly outline two approaches other than weight decay that one could expect to improve the generalization ability of an MLP. [6%]

Question 6

- (a) Why might one want to add *noise/jitter* to the training data when training a neural network? Should the noise be added to the inputs, the target outputs, or both? [8%]
- (b) What is meant by the terms *Hard Weight Sharing* and *Soft Weight Sharing*? Suggest how and when such processes might be usefully implemented in a neural network for practical applications. [8%]
- (c) Explain what is meant by the terms *Constructive Algorithm* and *Pruning Algorithm*, and outline when and why these algorithms might be useful. [9%]